

The Case for C++ in Embedded Systems

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Last Revised: 10/11/10

Beyond Language Choice

Reliably high-quality software based on:

- **Competent management + reasonable development process.**
 - ➔ Genuine concern for quality.
 - ➔ Suitable requirements analysis and change management.
 - ➔ Suitable scheduling/deployment decisions.
 - ➔ Suitable resource provision.
- **Competent developers.**
 - ➔ Architects, designers, programmers.
 - ➔ Understand problem domain + development tools.
 - ◆ Language, compiler, linker.
 - ◆ Unit testing tools, static + dynamic analysis tools.
 - ➔ Apply tools judiciously.
 - ◆ E.g., language features.

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Beyond Language Choice

Applicable regardless of language and problem domain.

- Bad management/process/developers ⇒ bad software.

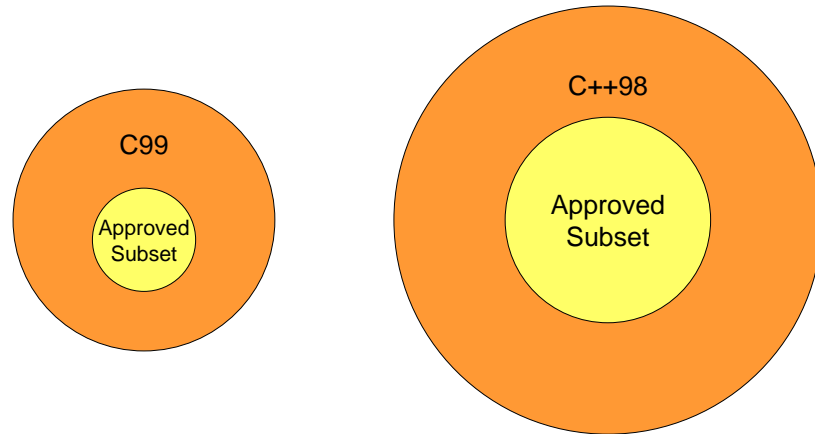
Language Usage Constraints

Usage constraints on C and C++ common.

- Generally stricter in embedded environments.
- Stricter still in safety-critical environments.
 - ➔ Higher cost of failure ⇒ more restrictive constraints.
- Language subsetting typically part of constraints.
 - ➔ From MISRA C and C++:
 - Identifiers declared in an inner scope shall not hide an identifier declared in an outer scope.
 - The comma operator shall not be used.
 - ➔ From MISRA C++:
 - A class destructor shall not exit with an exception.

Language Subsetting

So which is preferable?



The Case for C++

Constructors and destructors:

- **Automates initialization/finalization of UDTs.**
 - ➔ Can't forget.
 - ➔ Can't overlook control paths.
- **Enables generalized automatic resource management:**
 - ➔ RAII ("Resource Acquisition is Initialization"):
 - ◆ Constructor acquires or holds resource.
 - ◆ Destructor releases it.

RAII

Many standard library examples:

```
std::mutex m;                                // C++0x
{
  std::vector<int> v(1000);                    // allocate heap array
  std::ofstream f("data.txt");                // open file
  std::auto_ptr<Widget> p(new Widget);        // note heap object
  std::lock_guard<std::mutex> lg(m);          // lock mutex (C++0x)
  ...                                         // arbitrarily complex;
                                              // may throw
}                                              // unlock mutex
                                              // delete heap object
                                              // close file
                                              // deallocate heap array
```

RAII

Straightforward to customize:

```
class HoldResourceMgr {                       // e.g., std::auto_ptr
private:                                     // std::shared_ptr
  Resource r;
public:
  explicit HoldResourceMgr(const Resource& src)
  : r(src) {}
  ~HoldResourceMgr() { releaseResource(r); }
  ...                                       // handle copying
};
class AcquireResourceMgr {                   // e.g., std::vector,
private:                                     // std::ofstream,
  Resource r;                               // std::lock_guard
public:
  explicit AcquireResourceMgr(const DataForResource& d)
  : r(getResource(d)) {}
  ~AcquireResourceMgr() { releaseResource(r); }
  ...                                       // handle copying
};
```

Beyond Simple RAI

```

class Tracer { // log function calls & time spent in them
public:
    explicit Tracer( const char *funcName,
                    std::ostream& stream = std::clog)
    : fn(funcName), log(stream)
    {
        log << "Entering " << fn << '\n';
        startTime = std::time(NULL);
    }
    ~Tracer()
    {
        double ms = std::difftime(std::time(NULL), startTime) * 1000;
        log << "Leaving " << fn << '[' << ms << " ms]\n";
    }
private:
    const char * const fn; // function name
    std::time_t startTime;
    std::ostream& log;
};

```

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Beyond Simple RAI

Calls to

```

void someFunction( parameters )
{
    Tracer t(__func__); // start timer, log entry (C++0x)
    ...
} // stop timer, log exit

```

produce e.g., (in `std::clog`):

```

Entering someFunction
Leaving someFunction[1000 ms]

```

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Classes:

- **Encapsulate members by default.**
 - ➔ Private data members accepted as good practice.
- **Encourages interface/implementation separation.**
- **Encourages programming to interfaces.**
- **Facilitates changing internals w/o breaking client code.**

Changing Class Implementations

```
class Tracer {
private:
    const std::string fn;           // new
    MyCustomTimeClass startTime;   // internals
    std::ostream& log;

public:
    explicit Tracer(const char *funcName, // old
                   std::ostream& stream = std::clog); // interface
    ~Tracer();
};
void someFunction( parameters )
{
    Tracer t(__func__);           // as before
    ...
}
```

The Case for C++

Inheritance and virtual functions:

- Manifests cross-type interface commonality.

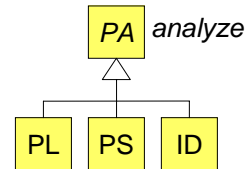
```
class Packet { ... };
```

```
class PacketAnalyzer {
public:
    virtual void analyze(const Packet& p) = 0;
    ...
};
```

```
class PacketLogger:
    public PacketAnalyzer { ... };
```

```
class PasswordSniffer:
    public PacketAnalyzer { ... };
```

```
class IntrusionDetector:
    public PacketAnalyzer { ... };
```



Acting Polymorphically

- Automates type-specific implementation selection.

```
bool getPacket(Packet);
```

```
std::vector<PacketAnalyzer*> analyzers;
```

```
...
```

```
Packet p;
```

```
while (getPacket(p)) {
    for (std::vector<PacketAnalyzer*>::iterator it = analyzers.begin();
         it != analyzers.end();
         ++it) {
        (*it)->analyze(p);           // perform appropriate analysis
    }
}
```

Gratuitous Animal Photo



Giant Anteater

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The Case for C++

Operator overloading:

- More readable UDT-based code:

```
std::vector<Widget> v;  
Widget w;
```

...

```
v[5] = w;           // std::vector::operator[], Widget::operator=
```

- ➔ Smart pointers an especially nice application:

- ◆ C++0x's `std::shared_ptr` automates reference counting.

```
p1 = p2;           // ++RC for *p1, --RC for *p2
```

- ◆ Can combine with RAII on temps returned from `operator->`:

```
p->f();           // possibly grab lock, invoke f, release lock;  
                // or start timer, invoke f, stop timer,  
                // etc.
```

- Inlined `operator()` faster than call through function pointer.

- ➔ Makes C++'s `sort` faster than C's `qsort`.

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The Case for C++

Templates:

- **Facilitate type safety.**

- ➔ The obvious kind, e.g., wrapping void* implementations:

```
template<typename T>           // offers push(T), pop(T)
class Stack { ... };

template<typename T>           // for when T is pointer type
class Stack<T*> {
public:
    void push(T* p) { data.push_back(p); }
    T* pop() {
        T* p = (T*) data.back();
        data.pop_back();
        return p;
    }
private:
    std::vector<void*> data;
};
```

- ➔ Clients see type-safe interfaces, object code only for void*s.

Dimensional Analysis

- ➔ The less obvious kind, i.e., user-defined type relationships.

```
template <int m, int d, int t>           // dimensionally safe
class Units {                           // wrapper for double
    ...
private:
    double value;                        // standardized value,
};                                         // e.g., kg, meters, etc.

typedef Units<0, 1, 0> Distance;
typedef Units<0, 0, 1> Time;
typedef Units<0, 1, -1> Velocity;        // distance/time
typedef Units<0, 1, -2> Acceleration;    // distance/time2

Distance d;
Time t1, t2;

Velocity v = d/t1;                       // okay
d = t1;                                   // error!
Acceleration a = v/t2;                   // okay
a = d/t1;                                 // error!
```

Dimensional Analysis

Used to statically dimensionally check, e.g.:

$$\frac{1}{X_0} = 4 \alpha r_e^2 \frac{N_A}{A} \{ Z^2 [L_{rad} - f(Z)] + Z L'_{rad} \}$$

Standard internal unit representation could have prevented 1999 loss of NASA's Mars Climate Orbiter.



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The Case for C++

More expressive standard library:

- **Containers and algorithms.**
 - ➔ Increases maintainability/comprehensibility.
 - ➔ Likely better vetted than home-grown versions.
 - ◆ Often more efficient, e.g., `std::remove`, `std::sort`.
 - ➔ Reduces tendency to always use array or list.
 - ◆ Deques, balanced trees, hash tables (C++0x) always on call.

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- **Better type safety:**

- ➔ Type-safe support for UDTs.

```
std::list<Widget*> lwp;           // lists are type-safe, use same
std::list<Gadget*> lgp;         // source code, probably same
                                // object code
```

- ➔ Different library “helpers” for single vs. array-like objects:

```
std::auto_ptr<int> api;          // object pointer
api[4] = 5;                      // error! operator[] unavailable
*api = 5;                         // okay
```

```
std::shared_ptr<int> spi;        // object pointer (C++0x)
spi[4] = 5;                       // error! still no operator[]
*spi = 5;                          // okay
```

```
std::deque<int> d;               // array-like object
d[4] = 5;                          // okay
*d = 5;                             // error! operator* unavailable
```

The Case for C++

Wider choice of third-party libraries:

- **C++ designed to take advantage of C APIs.**
 - ➔ Hence can call anything callable from C.
- **C not designed to call C++ APIs.**

Summary

Compared to C, C++ offers:

- Automatic UDT initialization and finalization.
- RAII-based resource management and derived techniques.
- UDT data encapsulation by default.
- Ability to express cross-type interface commonality.
- Automatic type-appropriate interface implementation selection.
- Natural operator syntax for UDTs.
- Greater type safety.
- More expressive standard library.
- Wider selection of third-party libraries.

Both languages requires developer competence in the language.

Further Information

- [“Abstraction and the C++ Machine Model,”](#) Bjarne Stroustrup, Keynote address at ICES04, December 2004.
 - ➔ Overview of strengths of C++ for embedded systems.
- [“OO Techniques Applied to a Real-time, Embedded, Spaceborne Application,”](#) Alexander Murray and Mohammad Shababuddin, *Proceedings of OOPSLA 2006*.
 - ➔ Describes use of OO and C++ in satellite software.
- [“Reducing Run-Time Overhead in C++ Programs,”](#) *Embedded Systems Conference*, Dan Saks, 1998 and subsequent years.
 - ➔ How to avoid common C++ performance “gotchas”.
 - ➔ 2002 paper available at http://www.open-std.org/jtc1/sc22/wg21/docs/ESC_SF_02_405_&_445_paper.pdf.
- [“C++ in Embedded Systems: Myth and Reality,”](#) Dominic Herity, *Embedded Systems Programming*, February 1998.
 - ➔ Dated (but good) overview of C++ vs. C.

Further Information

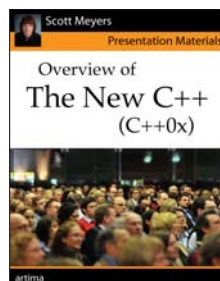
- [“Embedded Programming with C++,”](#) Stephen Williams, *Third USENIX Conference on Object-Oriented Technologies and Systems (COOTS)*, 1997.
 - ➔ Summarizes design/functionality/performance of a C++ runtime library for embedded systems.
- [“C++ in der Automotive-Software-Entwicklung,”](#) Matthias Kessler et al., *Elektronik automotive*, May 2006.
 - ➔ How C++ has been useful in embedded automotive software.
- [“Applied Template Metaprogramming in SIUNITS: the Library of Unit-Based Computation,”](#) Walter E. Brown, *Second Workshop on C++ Template Programming*, October 2001.

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About Scott Meyers



Scott is a trainer and consultant on the design and implementation of software systems, typically in C++. His web site,

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